

Consider the motion of a charge in an electric field \vec{E} , using the correct equations of special relativity. Let $\vec{E} = E_0 \hat{x}$ with E_0 constant. Consider a particle with initial conditions

$x=y=z=v_x=v_z=0$ at $t=0$, but with $v_y \neq 0$ at $t=0$.

- a) Solve for $v_x(t)$, $v_y(t)$, and $v_z(t)$. Also find simplified expressions for v_x , v_y when $t \rightarrow \infty$. (refer to Greiner pgs. 490-491)

→ Start from $\frac{d\vec{p}}{dt} = q(\vec{E} + \vec{v} \times \vec{B})$ where \vec{p} is the relativistic momentum. For each component this yields:

$$\frac{dp_x}{dt} = qE_0 \quad \frac{dp_y}{dt} = 0 \quad \frac{dp_z}{dt} = 0$$

the components of \vec{p} as functions of time are thus

$$p_x = qE_0 t \quad p_y = p_i \quad p_z = 0$$

One can now write the momentum 4-vector p_μ :

$$p_\mu = \left(\frac{T}{c}, qE_0 t, p_i, 0 \right) = (p_0, p_1, p_2, p_3) \quad (\text{Griffiths p. 97})$$

where T is the relativistic energy, $T = m_0 \gamma c^2$

Next, use the fact that $p^\mu p_\mu$ is invariant to write

$$p^\mu p_\mu = -m_0^2 c^2 = -(p_0)^2 + \vec{p} \cdot \vec{p}$$

$$-m_0^2 c^2 = -\frac{T^2}{c^2} + (qE_0 t)^2 + (p_i)^2 + 0$$

$$\Rightarrow T^2 = \underbrace{m_0^2 c^4}_{T_0^2} + c^2 p_i^2 + (c q E_0 t)^2$$

$$T = \sqrt{T_0^2 + (c q E_0 t)^2}$$

where T_0 = the initial total energy of the particle (Jackson p.

now use $\vec{p} = m_0 \gamma \vec{v}$, and $T = m_0 \gamma c^2$ to write

$$\vec{v} = \frac{\vec{p}}{m_0 \gamma} = \frac{\vec{p} c^2}{T}$$

thus, for the x-component, one gets

$$v_x(t) = \frac{dx}{dt} = \frac{p_x c^2}{T} = \frac{c^2 q E_0 t}{\sqrt{T_0^2 + (c q E_0 t)^2}} \Rightarrow \lim_{t \rightarrow \infty} v_x(t) = c$$

$$u = c q E_0 t$$

$$du = c q E_0 dt \Rightarrow dt = \frac{du}{c q E_0}$$

$$\int dx = \int \frac{c^2 q E_0 t}{\sqrt{T_0^2 + (c q E_0 t)^2}} dt \Rightarrow \int \frac{2u}{\sqrt{T_0^2 + u^2}} \frac{du}{2qE_0}$$

apply another substitution $T_0^2 + u^2 = \alpha$ $d\alpha = 2u du \Rightarrow du = \frac{d\alpha}{2u}$

$$\frac{1}{qE_0} \int \alpha^{-1/2} \frac{d\alpha}{2u} = \frac{1}{2qE_0} (2\alpha^{1/2}) = \frac{1}{qE_0} \sqrt{T_0^2 + (c q E_0 t)^2} + \text{constant}$$

so
$$x(t) = \frac{1}{qE_0} \sqrt{T_0^2 + (c q E_0 t)^2} - \frac{T_0}{qE_0}$$

v to match $x(0) = 0$

for $v_y(t)$ one gets:

$$\frac{dy}{dt} = \frac{p_y c^2}{T} = \frac{p_0 c^2}{\sqrt{T_0^2 + (c q E_0 t)^2}} \Rightarrow \lim_{t \rightarrow \infty} v_y(t) = 0$$

make substitution $u = \frac{c q E_0 t}{T_0}$ $du = \frac{c q E_0}{T_0} dt \Rightarrow dt = \frac{T_0}{c q E_0} du$

so integral becomes

$$\int dy = \frac{p_0 c^2 T_0}{T_0 q E_0} \int \frac{1}{\sqrt{1+u^2}} du = \frac{p_0 c}{q E_0} \sinh^{-1}(u)$$

thus
$$y(t) = \frac{p_0 c}{q E_0} \sinh^{-1}\left(\frac{c q E_0 t}{T_0}\right)$$

the motion is confined to the x - y plane, so $v_z = 0$ $z(t) = 0$

b) find the trajectory $x(y)$.

eliminate t by taking $\sinh\left[\frac{q E_0 y}{p_0 c}\right] = \frac{c q E_0 t}{T_0}$

so $t = \frac{T_0}{c q E_0} \sinh\left[\frac{q E_0 y}{p_0 c}\right]$ ← plug this into $x(t)$ to yield

$$x(y) = \frac{1}{q E_0} \sqrt{T_0^2 + T_0^2 \sinh^2\left(\frac{q E_0 y}{p_0 c}\right)} - \frac{T_0}{q E_0}$$

$$x(y) = \frac{T_0}{q E_0} \left[\cosh\left(\frac{q E_0 y}{p_0 c}\right) - 1 \right]$$